Cops and Robber on surfaces of constant curvature

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Example (Rado 1930s, Littlewood 1953, 1986)

A lion and a man move in an arena with the same maximum speed. Can the lion catch the man in finite time?



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Besicovitch 1952: no



Theorem (Bollobás, Leader, Walters, 2011)

There exists a compact metric space in which both players have winning strategies in the lion and man game.

Let D be a disk, I = [0,1]. Let $S = D \times I$ and take ℓ_{∞} metric on S.

- Lion keeps the disk coordinate the same as the man.
- The man moves away from lion's projectin and then uses Besicovitch's strategy.



The game of cops and robber on graphs

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Two players who alternate turns: one controlling all cops, the other controlling the robber.

The cops and robber occupy vertices of the graph. At the beginning of the game, robber chooses starting positions. On a turn, the cops or the robber can move to a neighboring vertex, or stay in the same position.

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Two players who alternate turns: one controlling all cops, the other controlling the robber.

The cops and robber occupy vertices of the graph. At the beginning of the game, robber chooses starting positions. On a turn, the cops or the robber can move to a neighboring vertex, or stay in the same position.

The cops win if after some finite number of rounds, one of them occupies the same vertex as the robber (capture). The robber wins if he can evade capture indefinitely.

The cop number c(G) of a graph G is the minimum number k such that k cops can win the game on G.

The game of cops and robber on graphs



Theorem (Aigner, Fromme, 1984)

If G is a planar graph, then $c(G) \leq 3$.



An induced subgraph H of G is k-guardable if after finitely many moves, k cops can arrange themselves in H such that the robber is immediately captured upon entering H.

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Isometric paths are 1-guardable.



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Surfaces

A *topological surface* is a connected topological space which is locally homeomorphic to an Euclidean disk.



Figure: A sphere, a torus and a projective plane.

Classification theorem for surfaces

Every compact topological surface is homeomorphic to either

- the sphere (g = 0)
- the connected sum of g tori for $g \ge 1$,
- or the connected sum of g + 1 real projective planes for $g \ge 0$, where g is the genus of the surface.



Conjecture (Mohar, 2009)

Let G be a graph embeddable in a surface of genus g. Then

 $c(G) \leq g^{\frac{1}{2}+o(1)}.$



 c(G) = O(g) (Quilliot, 1985; Andreae, 1986; Schroeder, 2001; Clarke, Fiorini, Joret, Theis, 2011; Erde, Lehner, Pitz, Bowler, 2019)

Conjecture (Meyniel, 1985)

Let G be a graph on n vertices. Then

$$c(G)=O(n^{\frac{1}{2}}).$$

- Best known bound: $c(G) = O\left(\frac{n}{2^{1-o(1)}\sqrt{\log_2(n)}}\right)$ (Lu, Peng, 2012; Frieze, Krivelevich, Loh, 2012; Scott, Sudakov 2011)
- Weak Meyniel conjecture: $c(G) = O(n^{1-\varepsilon})$ for some $\varepsilon > 0$.

A new game?

Similar to

- the game of cops and robber on graphs, and
- differential pursuit-evasion games (man and lion),

but

- not played just on graphs, and
- played in discrete-time.

Geodesic spaces

(X, d) metric space (x, y)-path is a continuous map $\gamma: [0, 1] \to X$ where $\gamma(0) = x$ and $\gamma(1) = y$ Length $\ell(\gamma) = \sup_{0=t_0 < t_1 < \dots < t_n = 1} \sum_{i=1}^n d(\gamma(t_{i-1}), \gamma(t_i))$

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intrinsic metric (shortest path distance) to obtain a geodesic space.

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X a compact geodesic space with intrinsic metric dThe game of cops and robber on the game space X with k cops (introduced by Mohar 2021):

- the first player controls the robber R, positioned at $r \in X$
- the second player controls k cops C_1, \ldots, C_k , positioned at $c = (c_1, \ldots, c_k) \in X^k$

The robber selects an initial position for all players: $Y_0 = (r^0, c_1^0, \dots, c_k^0) \in X^{k+1}$.

Robber also selects an agility function $\tau: \mathbb{N} \to \mathbb{R}_+$, $\sum_{n \ge 1} \tau(n) = \infty$.

After n-1 steps, the players are in position $(r^{n-1}, c_1^{n-1}, \ldots, c_k^{n-1}) \in X^{k+1}$. In the *n*th step, each player can move with unit speed up to a distance at most $\tau(n)$ from its current position.

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First, the robber moves to $r^n \in X$, $d(r^{n-1}, r^n) \leq \tau(n)$. This is revealed to the cops. Then each cop moves to a new position c_i^n , $d(c_i^{n-1}, c_i^n) \leq \tau(n)$.



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If the game never stops, then the value of the game is

$$v = \inf_{n \ge 0} \min_{i \in [k]} d(r^n, c_i^n).$$

If the value is 0, we say that the *cops win* the game; otherwise the *robber wins*. Note that the cops can win even if they never catch the robber.

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The minimum integer k such that k cops win the game on X is denoted by c(X) and called the *cop number* of X. If such k does not exist, then we set $c(X) = \infty$. Similarly we define the *strong cop number* $c_0(X)$ as the minimum k such that k cops can always catch the robber.
Guarding

Let X be the game space and let $A \subseteq X$. The *shadow* of the robber is $\sigma: X \to X$ such that $\sigma|_A = id|_A$ and $d(x, y) \ge d(\sigma(x), \sigma(y))$.



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If a cop comes to the point $\sigma(r)$, where r is the robber's position, then we say that the cop *caught* the shadow $\sigma(r)$ of the robber. It is easy to see that if after that robber ever enters A, then the cop can catch the robber. So we say that the cop *guards* A.

Known results (Mohar 2021)

- The min-max theorem holds for the game.
- If G is a graph and X is a metric graph obtained from G, then

$$c(G) \leq c(X) \leq c_0(X) \leq c(G) + 1.$$

- One cop can guard an isometric path.
- If S is a topological sphere, then $c(S) \leq 3$.

2-dimensional ball

Cop's strategy:

- O cop moves to the center of the disk
- Operation of the same distance as robber, ending his move on the line connecting the center of the disk and robber's position while getting as close to robber as possible



2-dimensional ball

Properties:

• cop in position c can guard the circle of radius d(O, c)



2-dimensional ball

- cop in position c can guard the circle of radius d(O, c)
- distance between cop and robber is decreasing

$$(d(r^{n+1}, c^{n+1}) \le d(r^n, c^n))$$



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- distance between cop and robber is decreasing $(d(r^{n+1}, c^{n+1}) \le d(r^n, c^n))$
- the sequence $\{d(r^n, c^n)\}_n$ converges
- if $\lim_{n\to\infty} d(r^n, c^n) = 0$, then cop can get arbitrarily close to robber
- otherwise we suppose that $\lim_{n\to\infty} d(r^n, c^n) = \ell > 0$ and prove that this leads to a contradiction



n-dimensional ball

Theorem (IMW, 2022)

If $n \ge 1$, then $c(B^n) = 1$.

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Similar argument as for the differential pursuit-evasion game (Croft 1964).



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Theorem (Killing-Hopf, 1891/1926)

Any compact Riemannian surface of constant curvature -1 (resp. 1, 0) is isometric to \mathcal{D}^2/Γ (resp. S^2/Γ , \mathbb{R}^2/Γ) where Γ is a group of isometries on \mathcal{D}^2 (resp. S^2 , \mathbb{R}^2) acting freely and properly discontinuously.



Figure: $\mathcal{D}^2 = \{(x, y) | x^2 + y^2 \le 1\}$ equipped with the metric $ds^2 = \frac{dx^2 + dy^2}{(1 - x^2 - y^2)}$

Sphere

One cop can guard an isometric path (Mohar 2021). How can this be applied to the sphere S^2 ?



 $\implies c(S^2) \leq 3$

n-dimensional sphere

One cop can guard a great circle in S^n .



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C&R on surfaces of constant curvature

n-dimensional sphere

Theorem (IMW, 2022)

If $n \ge 1$, then $c(S^n) = 2$ and $c_0(S^n) = n + 1$.



 c_0 result follows similarly as for the differential pursuit-evasion game (Satimov, Kuchkarov 2000).

Euclidean torus

Theorem (IMW, 2022)

If $n \ge 2$, then $c(T^n) = 2$ and $c_0(T^n) = n + 1$.



If C is a covering space of X that locally preserves distances, then $c(X) \leq c(C)$.



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Euclidean torus

Theorem (IMW, 2022)

If $n \ge 2$, then $c(T^n) = 2$ and $c_0(T^n) = n + 1$.



If $g \ge 2$ and S_g is a compact hyperbolic surface of genus g, then $c(S_g) = 2$.

 S_g has the Poincaré disk as a covering space. Example:





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Hyperbolic surfaces



Strategy of cop c_1 if the robber makes a step "up":

(a) the cop c_1 moves towards B if this keeps the "robber above the cop"

(b) otherwise, the cop c_1 moves to the geodesic through r which is orthogonal to h, as close to the robber as possible

If $g \ge 2$ and S_g is a compact hyperbolic surface of genus g, then $c(S_g) = 2$.

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If $g \ge 2$ and S_g is a compact hyperbolic surface of genus g, then $c(S_g) = 2$.

Theorem (IMW, 2024)

If M is a compact hyperbolic manifold, then c(M) = 2.

Game on surfaces of genus g

Suppose S_g is a compact geodesic surface of genus g.

Theorem (Mohar, 2022)

 $If g \geq 1, \ c(S_g) \leq 2g+1.$

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Game on surfaces of genus g

Suppose S_g is a compact geodesic surface of genus g.

Theorem (Mohar, 2022)

 $\textit{If } g \geq 1, \ c\bigl(S_g\bigr) \leq 2g+1.$

Conjecture (Mohar, 2022)

For $g \to \infty$, $c(S_g) \le g^{\frac{1}{2} + o(1)}$.

Classification of surfaces of constant curvature



Figure: Spherical, Euclidean and hyperbolic geometry.

Classification of surfaces of constant curvature



Figure: Spherical, Euclidean and hyperbolic geometry.

Results for hyperbolic manifolds, S^n and T^n + some technicalities \implies

Theorem (IMW, 2024)

If S_g has constant curvature, then $c(S_g) = 2$.
What is $c_0(S_g)$ for a hyperbolic surface S_g of genus g?

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- Best general upper bound is O(g). Can it be improved at least to $c \cdot g$ for some constant c < 1.

What is $c_0(S_g)$ for a hyperbolic surface S_g of genus g?

- There exist nice hyperbolic surfaces of genus g ≥ 2, where 6 cops suffice and 3 cops are needed. What are the correct values?
- Best general upper bound is O(g). Can it be improved at least to $c \cdot g$ for some constant c < 1.
- Is the strong cop number bounded by a constant on hyperbolic surfaces?

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Conjecture (Mohar, 2022)

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- First step would be to improve the known upper bound (2g + 1).
- An additional direction is to find more properties of spaces that guarantee a finite (or constant) strong cop number.

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Every compact geodesic space X has a finite cop number, i.e. $c(X) < \infty$.

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This is not true for $c_0(X)$.

Proposition (IMW, 2022)

There exists a compact geodesic space X with c(X) = 1 and $c_0(X) = \infty$.

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Conjecture (Mohar 2021)

Every compact geodesic space X has a finite cop number, i.e. $c(X) < \infty$.

This is not true for $c_0(X)$.

Proposition (IMW, 2022)

There exists a compact geodesic space X with c(X) = 1 and $c_0(X) = \infty$.

Also not true for c(X)!

Theorem (Georgakopoulos, 2023)

There exists a compact geodesic space X homeomorphic to S^3 with $c(X) = \infty$.

Open problems

Open questions (Georgakopoulos, 2023):

- Obes every compact metrizable topological space X admit a metric d such that c((X, d)) is finite?
- Obes every finite-dimensional, compact, Riemannian manifold M have finite c(M)?
- Is c(X) finite if we add another property to the compact geodesic space X, for example having a finite doubling constant or being homogeneous?

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Thank you!