

# On Star Partition of Split Graphs

D Divya    S Vijayakumar

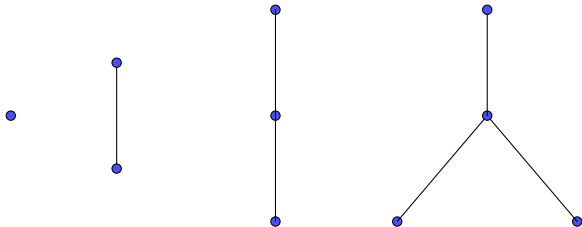
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## Star

A graph that is isomorphic to  $K_{1,r}$ , for some  $r \geq 0$ , is called a **star**.

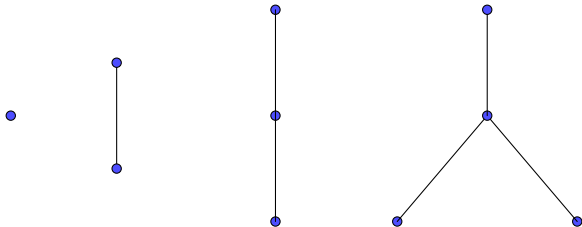
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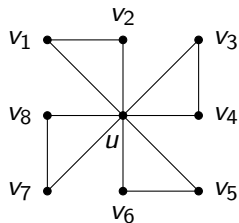
**Note:** Each star has a **center** vertex.

## Stars in a Graph

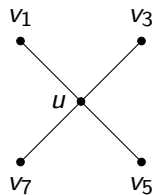
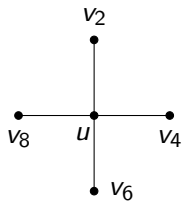
A set  $S$  of vertices from a graph  $G$  is called a **star of  $G$**  if the induced subgraph  $G[S]$  is a star.

**Note:** A star  $S$  in a graph  $G$  partitions into an *independent set*  $I$  and a singleton set  $\{x\}$ :  $S = \{x\} \cup I$ .

# Example



$$G = F_4$$



# Definition

## Star Cover

A collection of stars  $\mathcal{S} = \{V_1, \dots, V_k\}$  of a graph  $G$  is called star cover of  $G$  if  $V_1 \cup \dots \cup V_k = V(G)$ .

## Star Partition

A star cover  $\mathcal{S} = \{V_1, \dots, V_k\}$  of a graph  $G$  is called a *star partition* of  $G$  if the stars in it are disjoint.

## $sc(G)$ and $sp(G)$

- The size of a minimum star cover of  $G$  is called the **star cover number of  $G$**  and is denoted  $sc(G)$ .
- The size of a minimum star partition of  $G$  is called the **star partition number of  $G$**  and is denoted  $sp(G)$ .

**Note:** The sizes of the stars do not matter!

**Note:**  $sc(G) \leq sp(G)$ .



# Example

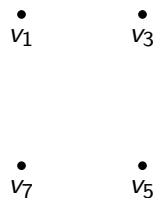
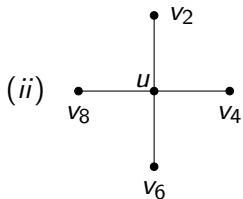
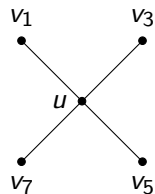
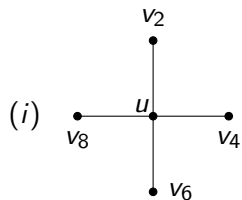
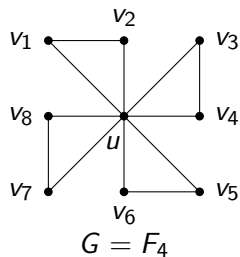


Figure: (i)  $sc(G) = 2$ . (ii)  $sp(G) = 5$ .

# The Problems

## MIN STAR COVER

**Instance** : A graph  $G$ .

**Goal** : A minimum star cover of  $G$ .

## MIN STAR PARTITION

**Instance** : A graph  $G$ .

**Goal** : A minimum star partition of  $G$ .

# The Decision Versions

## STAR COVER(D)

**Instance:** A graph  $G$  and a positive integer  $k$ .

**Question:** Does  $G$  have star cover of size at most  $k$ ?

## STAR PARTITION(D)

**Instance:** A graph  $G$  and a positive integer  $k$ .

**Question:** Does  $G$  have star partition of size at most  $k$ ?

## A Note on Triangle-free ( $K_3$ -free) Graphs

For any triangle-free graph  $G$ ,

$$sc(G) = sp(G) = \gamma(G).$$

## Some Facts

- For any graph  $G$ :
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- Has a simple 2-approximation algorithm.
- Has linear time exact algorithms for claw-free split graphs.
- Complexity Status **open** for  $K_{1,4}$ -free split graphs.



A split graph  $G = (C \cup I, E)$  is  $K_{1,r}$ -free: Each vertex  $x$  in  $C$  has at most  $r - 1$  neighbours in  $I$ .

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**In This Talk:** We mainly study those split graphs  $G$  for which each vertex  $z$  in  $I$  has at most a constant number of neighbours, in  $I$ : i.e.,  $d(z) \leq s$  for a small fixed  $s$ .

## Definition

Let  $G = (C \cup I, E)$  be a split graph and let  $r$  and  $r_1 \leq \dots \leq r_k$  be non-negative integers. Then:

- 1  $G$  is called an  $r$ -split graph if  $d(v) = r$  for each  $v \in I$ .

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- 2  $G$  is called an  $(r_1, \dots, r_k)$ -split graph if  $d(v)$  equals one of  $r_1, \dots, r_k$  for each  $v \in I$ .

# Literature Survey

## NP-hardness Results

STAR COVER(D) and STAR PARTITION(D) are NP-hard for

- Chordal bipartite graphs [15]
- $(C_4, C_6, \dots, C_{2t})$ -free bipartite graphs for every fixed  $t \geq 2$  [7]
- Subcubic bipartite planar graphs [9, 19]
- $K_{1,5}$ -free split graphs [19]
- Line graphs [5, 19]
- Co-tripartite graphs [11, 19].

Also:

- Deciding whether an input graph can be covered by *or* partitioned into three stars is NP-complete [19].
- Deciding whether an input graph can be covered by *or* partitioned into at most two stars has polynomial time algorithms.

# Literature Survey

## Polynomial Time Algorithms

STAR COVER(D) and STAR PARTITION(D) have polynomial time algorithms for

- bipartite permutation graphs [2, 8].
- convex bipartite graphs [1, 4].
- doubly-convex bipartite graphs [1].
- trees [3].
- trivially perfect graphs [12].
- co-trivially perfect graphs [12].
- claw-free split graphs [14].
- double-split graphs [13].

# Literature Survey

## Approximation and Inapproximation Results

- It is NP-hard to approximate STAR PARTITION(D) within  $n^{1/2-\epsilon}$  for all  $\epsilon > 0$  [19, 21].
- STAR COVER(D) and STAR PARTITION(D) do not have any polynomial time  $c \log n$ -approximation algorithm for some constant  $c > 0$  unless  $P = NP$  [20].
- For  $K_{1,r}$ -free graphs
  - ① STAR PARTITION(D) has a polynomial time  $r/2$ -approximation algorithm [10, 19].
  - ② STAR COVER(D) has a polynomial time  $H_r$ -approximation algorithm [12]
- STAR COVER(D) and STAR PARTITION(D) have a polynomial time
  - ① A 2-approximation algorithm for split graphs [19];
  - ②  $O(\log n)$ -approximation algorithms for triangle-free graphs [20];
  - ③  $(d + 1)$ -approximation algorithm for triangle-free graphs of degree at most  $d$  [20].

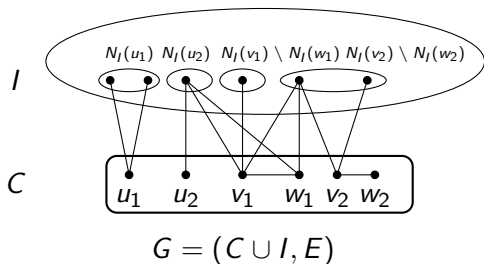
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## Parameterized Complexity Results

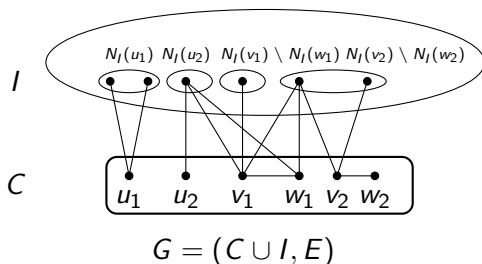
- With solution size as the parameter, both  $\text{STAR COVER}(D)$  and  $\text{STAR PARTITION}(D)$  are
  - 1  $W[2]$ -complete for bipartite graphs.
  - 2 Fixed parameter tractable for graphs of girth at least five.
- With respect to structural parameters:
  - 1 With vertex cover number as the parameter, the star partition problem is fixed parameter tractable.
  - 2 With treewidth as the parameter, the star partition is fixed parameter tractable on bounded treewidth graphs.



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$s = \#$  stars in star partition with one vertex from  $C$ .

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Here  $s = 2$  and  $t = 2$ .

**Note:**  $s + 2t = |C|$ .

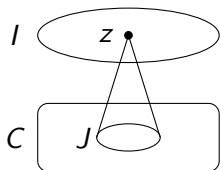
*Better if the centers can **always** be in  $C$ !*

# Structure of Star Partitions of Split Graphs

## Lemma

*Let  $G = (C \cup I, E)$  be a connected split graph. If  $G$  has a star partition of size  $k$ , then it also has a star partition  $\mathcal{S}$  of size at most  $k$  such that each star in  $\mathcal{S}$  has its center in  $C$ .*

# Proof

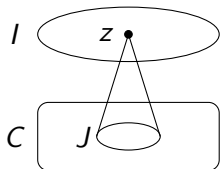


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$$\begin{array}{c} z \\ \bullet \\ | \\ \bullet \\ x' \\ Z = \{z, x'\} \end{array}$$

Suppose a star partition  $\mathcal{S}$  has a star  $Z = \{z\} \cup J$  with its center  $z$  in  $I$ .

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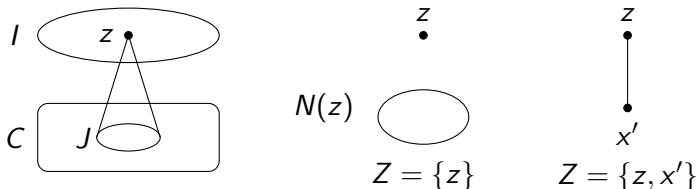
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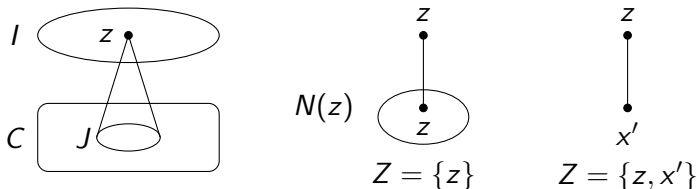
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- (a) For any  $u \in C$ ,  $X = \{u\} \cup N_I(u)$  is *the* maximal star of  $G$  with **only** its center  $u$  from  $C$ .

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- (b) For any *ordered pair*  $v, w \in C$ ,  $X = \{v, w\} \cup [N_I(v) \setminus N_I(w)]$  is the maximal star of  $G$  with  $v$  and  $w$  as **the center–non-center pair** from  $C$ .

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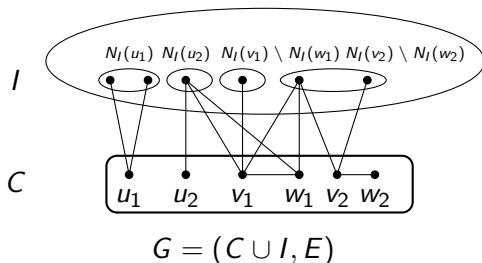
If  $G = (C \cup I, E)$  is a **connected split graph**, enough to consider those stars for which the centers are in  $C$ .

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Thus, such a star partition  $\mathcal{S}$  suggests a **special** three-way partition of  $C$ .

# Example



$s = \#$  stars in star partition with one vertex from  $C$ .

$t = \#$  stars in star partition with two vertices from  $C$ .

Here  $s = 2$  and  $t = 2$ .

**Note:**  $s + 2t = |C|$ .

## An $(s, t)$ -partition of $C$

### Definition

Let  $G = (C \cup I, E)$  be a connected split graph with  $|C| = q$ . Suppose  $C$  partitions into three *ordered* sets

$$S = \{u_1, \dots, u_s\}, T_1 = \{v_1, \dots, v_t\}, T_2 = \{w_1, \dots, w_t\}$$

such that

$$N_I(u_1) \cup \dots \cup N_I(u_s) \cup [N_I(v_1) \setminus N_I(w_1)] \cup \dots \cup [N_I(v_t) \setminus N_I(w_t)] = I.$$

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An  $(s, t)$ -partition of  $C$  corresponds to a star partition of  $G$  of size  $s + t$ .



## Results on $(s, t)$ -partition of $C$

### Lemma

*Let  $G = (C \cup I, E)$  be a connected split graph with  $|C| = q$ . Let  $s$  and  $t$  be non-negative integers such that  $s + 2t = q$ . Then  $G$  has a star partition of size  $k = s + t$  if and only if  $C$  has an  $(s, t)$ -partition.*

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### Lemma

*Let  $G = (C \cup I, E)$  be a connected split graph with  $|C| = q$  and  $|I| = p$  and let  $s, t$  be any non-negative integers. Then we can decide whether  $C$  has an  $(s, t)$ -partition in time  $O(q^{2t+1}p)$ . LEX Reference.*

# A Characterization of Split Graphs with $sp(G) = \omega(G)$

## Theorem

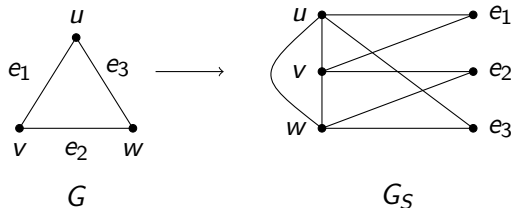
Let  $G = (C \cup I, E)$  be a connected split graph with  $C = \{x_1, \dots, x_q\}$  as a maximum clique of  $G$  so that  $\omega(G) = |C| = q$ . Then  $sp(G) = \omega(G)$  if and only if for every ordered pair  $(i, j)$  with  $1 \leq i, j \leq q$  and  $i \neq j$ ,

- either  $N_I(x_j)$  has a vertex of degree one
- or  $N_I(x_i) \cap N_I(x_j)$  has a vertex of degree two (or both).

# The Case of 2-Split Graphs

## Definition

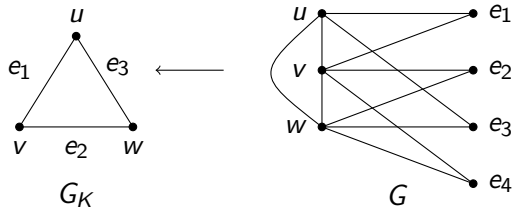
Let  $G = (V, E)$  be any graph. Then the **split division** of  $G$ , denoted  $G_S$ , is the 2-split graph  $G_S = (C \cup I, E_S)$  obtained from  $G$  by taking  $C = V(G)$  as the clique part and  $I = E(G)$  as the independent part and making each vertex  $e = uv$  in  $I = E(G)$  adjacent to its end vertices  $u$  and  $v$  in  $C = V(G)$ .



# The Case of 2-Split Graphs

## Definition

Let  $G = (C \cup I, E)$  be a 2-split graph. Then the **kernel** of  $G$ , denoted  $G_K$ , is the graph  $G_K = (V_K, E_K)$  with vertex set  $V_K = C$  and edge set  $E_K = \{vw \mid N_G(u) = \{v, w\} \text{ for some } u \in I\}$ .

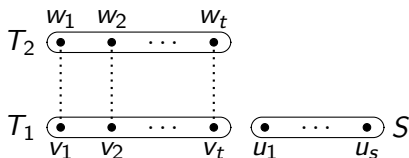


# The Case of 2-Split Graphs

## Lemma

Let  $G = (C \cup I, E)$  be a 2-split graph and let  $G_K = (V_K, E_K)$  be its kernel. Then  $G$  has  $S = \{u_1, \dots, u_s\}$ ,  $T_1 = \{v_1, \dots, v_t\}$  and  $T_2 = \{w_1, \dots, w_t\}$  as an  $(s, t)$ -partition of  $C$  if and only if  $G_K$  has

- $v_j w_j$  as a non-edge for each  $1 \leq j \leq t$ ;
- $\{w_1, \dots, w_t\}$  as an independent set.



$(s, t)$ -partition of  $C$ .

## Theorem

*STAR PARTITION(D) is NP-complete even when restricted to  $K_{1,5}$ -free 2-split graphs.*



# The Reduction

Reduction from the following NP-complete problem.

## 2-3-INDEPENDENT SET

**Input** : A graph  $G = (V, E)$  with  $|V| = 2\ell$  and  $d(v) = 2$  or  $3$ , for all  $v \in V$ , also  $G$  has a perfect matching.

**Question** : Does  $G$  have an independent set of size  $k$ , where  $k \leq \ell - 2$  .

- This NP-completeness result on independent sets follows from a simple reduction from the MAX2SAT problem restricted to those instances in which
  - ▶ each clause has exactly two literals,
  - ▶ each variable occurs exactly *thrice*,
  - ▶ each literal occurs at least *once*.
- MAX2SAT restricted to this instances is NP-hard [17].

# The Reduction

Let  $(G, k)$  be an instance of the 2-3 independent set problem.

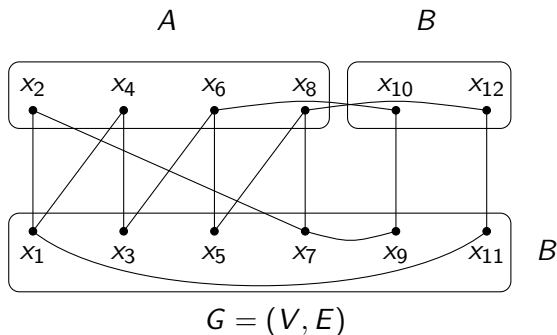
Transformed instance  $(G', k')$  with  $G_s = (C \cup I, E_s)$  and  $k' = 2\ell - k$ .

**Note:**  $G_s = (C \cup I, E_s)$  is  $K_{1,5}$ -free split graph.

**Claim:**  $G$  has an independent set of size  $k$  if and only if  $G_s$  has a star partition of size  $k' = 2\ell - k$ .

Suppose  $G$  has an independent set of size  $k$ , say  $A$

- $k = |A| = 4$ .



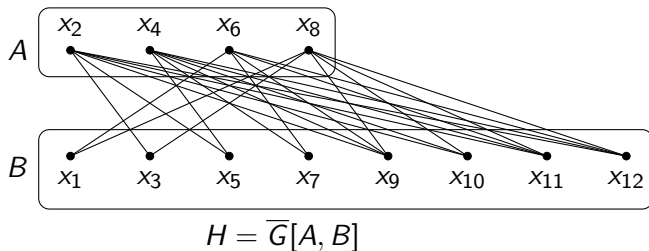
- Let  $B = V(G) \setminus A$ .

Suppose  $G$  has an independent set of size  $k$ , say  $A$

- Let  $H = (A \cup B, E_H)$  be the bipartite graph with

$$E_H = \{ab : a \in A, b \in B \text{ and } ab \notin E(G)\}.$$

- $H$  satisfies Hall's condition.
- So,  $H$  has a matching, say  $M$ , saturating  $A$ .

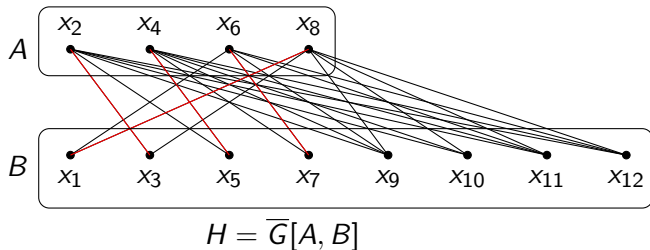


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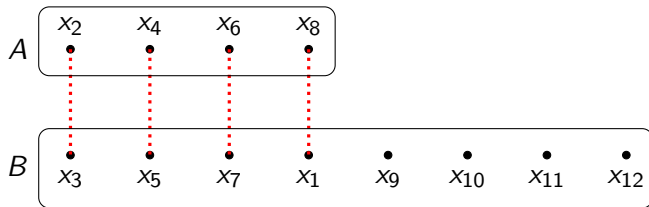


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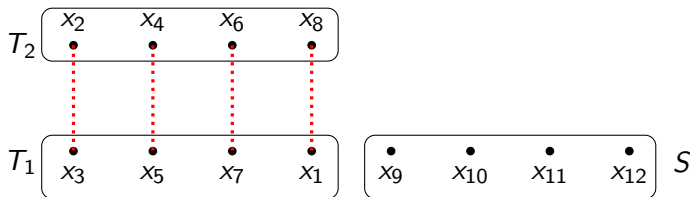
Matching of non-edges in  $G$

Suppose  $G$  has an independent set of size  $k$ , say  $A$

- Let  $H = (A \cup B, E_H)$  be the bipartite graph with

$$E_H = \{ab : a \in A, b \in B \text{ and } ab \notin E(G)\}.$$

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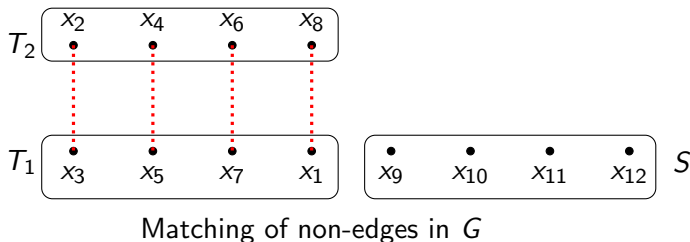
Matching of non-edges in  $G$

Suppose  $G$  has an independent set of size  $k$ , say  $A$

- Let  $H = (A \cup B, E_H)$  be the bipartite graph with

$$E_H = \{ab : a \in A, b \in B \text{ and } ab \notin E(G)\}.$$

- $H$  satisfies Hall's condition.
- So,  $H$  has a matching, say  $M$ , saturating  $A$ .



- Form an  $(2(\ell - k), k)$ -partition of the clique part  $C$  of the 2-split graph  $G_S$ .
- Then, by Lemma,  $G_S$  has a star partition of size  $2\ell - k$ .



## Converse

Suppose  $G_S = (C \cup I, E_S)$  has a star partition of size  $2\ell - k$ .

Now, since  $|C| = |V(G)| = 2\ell$ ,  $C$  has an  $(2(\ell - k), \ell)$ -partition, say  $S = \{u_1, \dots, u_{2(\ell-k)}\}$ ,  $T_1 = \{v_1, \dots, v_k\}$  and  $T_2 = \{w_1, \dots, w_k\}$ .

But  $G_S$  is a 2-split graph with  $G$  as its kernel.

So, by Lemma,  $\{w_1, \dots, w_k\}$  is an independent set of  $G$  of size  $k$ .

## More NP-completeness Results

### Theorem

*It is NP-complete to decide whether  $sp(G) = \lceil \omega(G)/2 \rceil$  even when the instances are restricted to  $K_{1,6}$ -free 2-split graphs.*

### Theorem

*STAR PARTITION(D) is NP-complete even when restricted to  $(1, r)$ -split graphs for each fixed  $r \geq 2$ .*

# Parameterized Complexity Results

*We study the problems in the Parameterized Complexity Framework and consider three natural parameterizations.*

**Parameterization I:** Solution Size as the Parameter.

## STAR PARTITION(D)

**Instance** : A connected split graph  $G$  and a positive integer  $k$ .

**Parameter** :  $k$ .

**Question** : Does  $G$  have a star partition of size  $k$ ?

## Theorem

STAR PARTITION(D) is fixed parameter tractable. In fact, it has an  $O((2k)^{2k+1}n)$  time algorithm.

## Proof.

- Let  $G = (C \cup I, E)$  and suppose  $|C| = q$  and  $|I| = p$ .
- Then  $q/2 \leq sp(G) \leq q$ . So, we now assume that  $q/2 \leq k \leq q$ .
- By Lemma 4,  $G$  has a star partition of size  $k$  if and only if  $C$  has an  $(s, t)$ -partition for  $(s, t) = (2k - q, q - k)$ .
- Now  $q \leq 2k$  and  $t = q - k \leq k$ .
- Lemma 5, for any non-negative integer pair  $(s, t)$ , we can decide whether  $C$  has an  $(s, t)$ -partition in time  $O(q^{2t+1}p)$ .
- This implies that deciding whether  $C$  has an  $(s, t)$ -partition with  $(s, t) = (2k - q, q - k)$  can be decided in time  $O((2k)^{2k+1}n)$



## Parameterization II: Parameterizing above a Quaranteed Value

**Note:** For any graph  $G$ ,  $sp(G) \geq \lceil \omega(G)/2 \rceil$ .

### STAR PARTITION (AQ)

**Instance :** A graph  $G$  and a positive interger  $k$ .

**Parameter :**  $k$ .

**Question :** Is  $sp(G) \leq \lceil \omega(G)/2 \rceil + k$ ?

### Theorem

STAR PARTITION (AQ) is *para-NP-hard* even when restricted to either (1)  $K_{1,6}$ -free  $(0, 2)$ -split graphs or (2)  $K_{1,5}$ -free  $(0, 1, 3)$ -split graphs.

## Parameterization III: Saving $k$ Stars

**Note:** For any connected split graph  $G$ ,  $sp(G) \leq \omega(G)$ .

### STAR PARTITION ( $\omega - k$ )

**Instance** : A connected split graph  $G$  and a positive integer  $k$ .

**Parameter** :  $k$ .

**Question** : Does  $G$  have a star partition of size  $\omega(G) - k$ ?

### Theorem

STAR PARTITION ( $\omega - k$ ) is  $W[1]$ -hard even for  $(1, 2)$ -split graphs.

## $W[1]$ -hardness: The Reduction

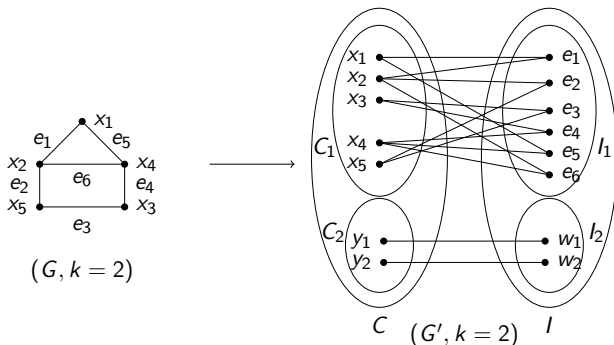
- We give a polynomial time FPT reduction from the independent set problem parameterized by the solution size  $k$ .
- The latter problem is  $W[1]$ -complete [6].

# The Reduction

Let  $(G, k)$  be an instance of the independent set problem.

We transform this into a split graph  $G' = (C \cup I, E')$ , preserving the parameter  $k$ .

$$G \rightarrow G_s = (C_1 \cup I_1, E) \rightarrow G' = G_s \cup kK_2$$



- $\omega(G') = n + k$



Claim:  $G$  has an independent set of size  $k$  if and only if  $sp(G') \leq \omega(G') - k$

- 1  $G$  has an independent set of size  $k$  if and only if it has a vertex cover of size  $n - k$ .
- 2  $G$  has a vertex cover of size  $n - k$  if and only if, in  $G'$ ,  $n - k$  vertices of  $C_1$  are adjacent to all vertices in  $I_1$ .
- 3 The latter happens if and only if  $sp(G') \leq n = \omega(G') - k$ .

## Theorem

STAR PARTITION  $(\omega - k)$  is in the class  $W[3]$ .

**Proof:** We construct a circuit  $\mathcal{C}$  such that it has a satisfying assignment of size  $k$  if and only if  $G$  has a star partition of size  $\omega(G) - k$ .

Or, if and only if,  $G$  has an  $(s, t)$ -partition with  $t = k$ .

## Fact

Suppose  $(S, T_1, T_2)$  is an  $(s, t)$ -partition of  $C$ , where  $C = \{c_1, \dots, c_q\}$ .

Without loss of generality, let:

- $S = \{c_1, \dots, c_s\}$ .
- $T_1 = \{c_{s+1}, \dots, c_{s+t}\}$ .
- $T_2 = \{c_{s+t+1}, \dots, c_{s+2t=q}\}$ .

Then  $s + 1, \dots, s + t, s + t + 1, \dots, s + 2t = q$  are distinct.

# The Construction of the Circuit

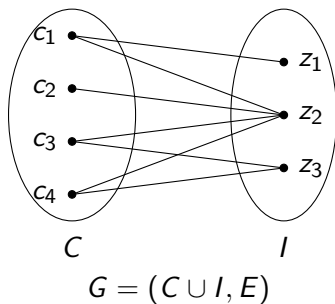
We have  $C = \{c_1, \dots, c_q\}$ . Let  $I = \{z_1, \dots, z_p\}$ .

**Notation:**  $X_i = N_I(c_i)$  and  $X_{ij} = X_i \setminus X_j = N_I(c_i) \setminus N_I(c_j)$  ( $i \neq j$ ).

The circuit will have an input variable corresponding to each  $X_{ij}$ .

A satisfying assignment of size  $k$  pick the sets  $T_1$  and  $T_2$  of an  $(s, t)$ -partition for which  $|T_1| = |T_2| = k$ .

## The Construction of the Circuit: An Example



$$X_1 = \{z_1, z_2\};$$

$$X_2 = \{z_2\};$$

$$X_3 = \{z_2, z_3\};$$

$$X_4 = \{z_2, z_3\};$$

$$X_{1,2} = X_{1,3} = X_{1,4} = \{z_1\};$$

$$X_{2,1} = X_{2,3} = X_{2,4} = \emptyset;$$

$$X_{3,1} = X_{3,2} = \{z_3\}; X_{3,4} = \emptyset;$$

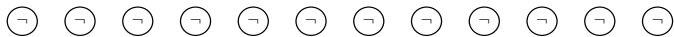
$$X_{4,1} = X_{4,2} = \{z_3\}; X_{4,3} = \emptyset;$$

# Circuit

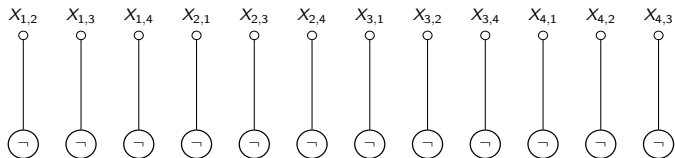
$X_{1,2}$   $X_{1,3}$   $X_{1,4}$   $X_{2,1}$   $X_{2,3}$   $X_{2,4}$   $X_{3,1}$   $X_{3,2}$   $X_{3,4}$   $X_{4,1}$   $X_{4,2}$   $X_{4,3}$   
○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○ ○

# Circuit

$X_{1,2}$   $X_{1,3}$   $X_{1,4}$   $X_{2,1}$   $X_{2,3}$   $X_{2,4}$   $X_{3,1}$   $X_{3,2}$   $X_{3,4}$   $X_{4,1}$   $X_{4,2}$   $X_{4,3}$

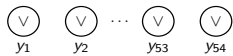
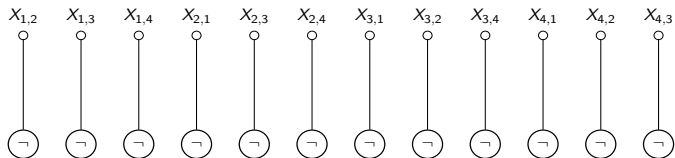


# Circuit

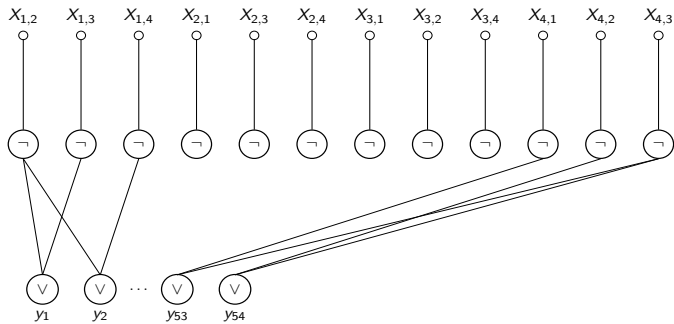




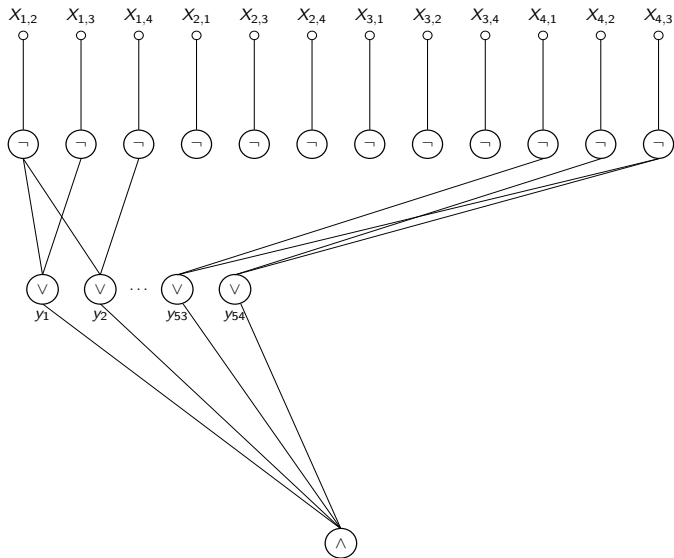
# Circuit



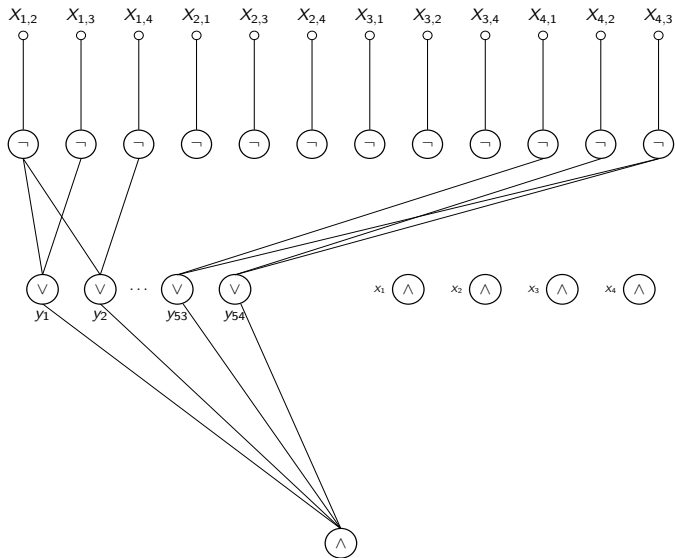
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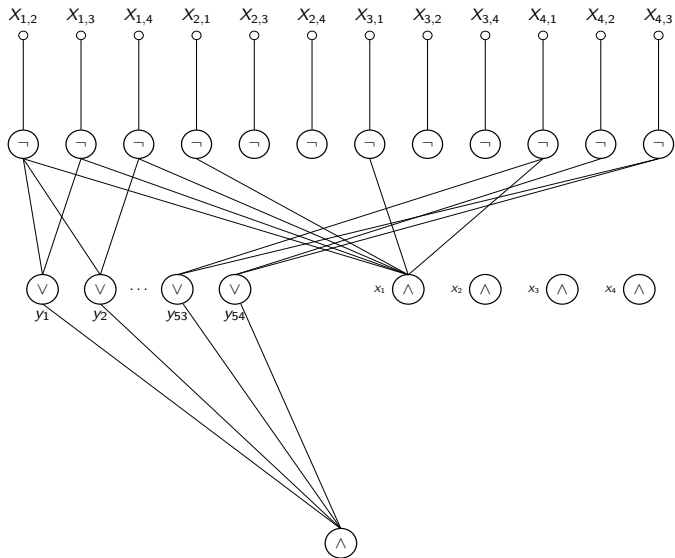
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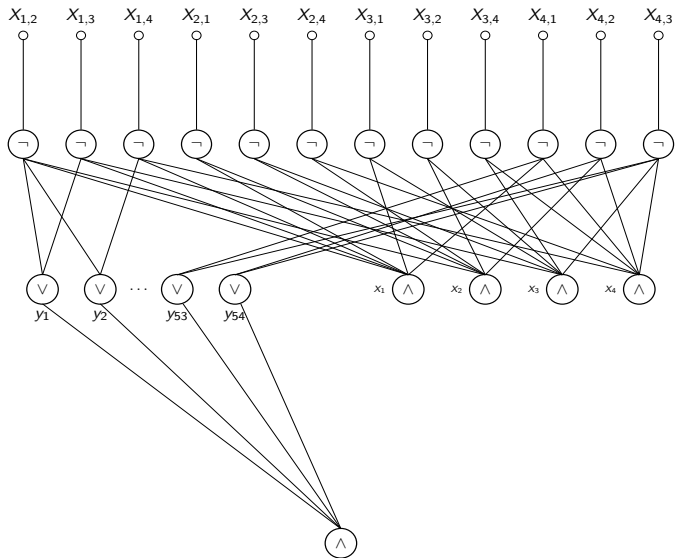
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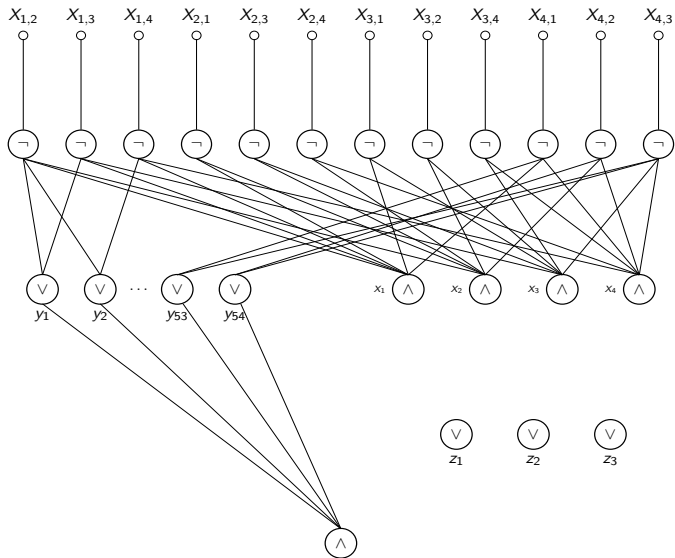
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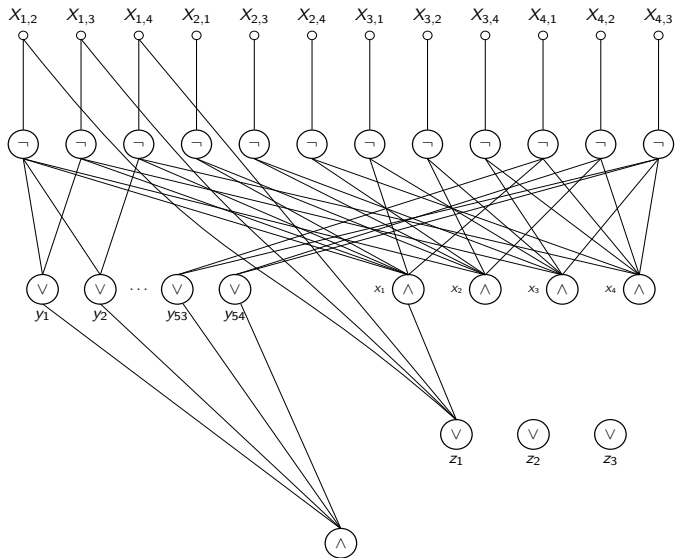
# Circuit



# Circuit

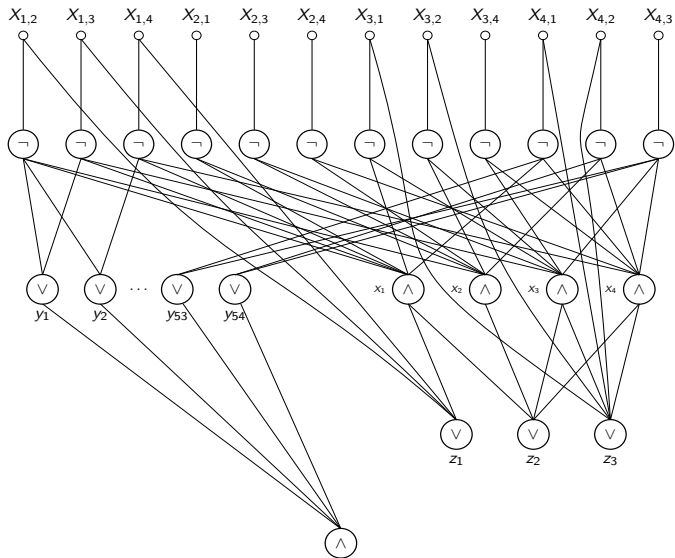


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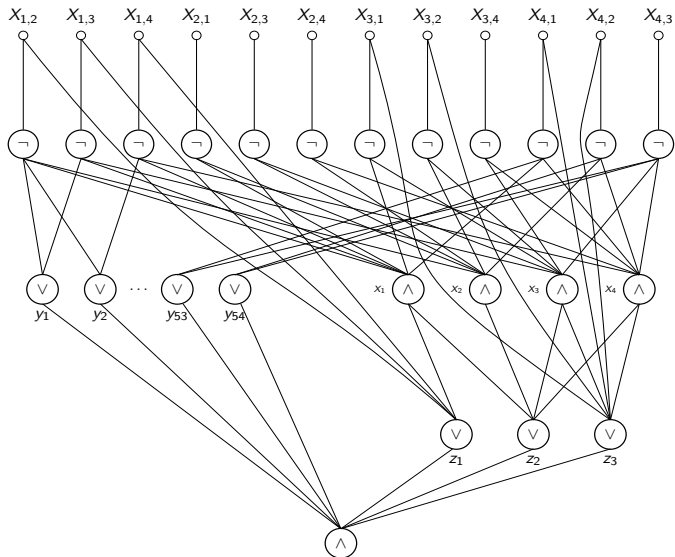




# Circuit



# Circuit



*Claim:* The circuit  $\mathcal{C}$  has a satisfying assignment of size  $k$  if and only if  $sp(G) = \omega(G) - k$ .

Suppose the circuit  $\mathcal{C}$  has a satisfying assignment of size  $k$ .

- Without loss of generality, assume that the  $k$  variables  $X_{s+1,s+k+1}, X_{s+2,s+k+2}, \dots, X_{s+k,s+2k}$  are assigned the value 1.
- Then, by the design of the circuit  $S = \{c_1, c_2, \dots, c_s\}$ ,  $T_1 = \{c_{s+1}, c_{s+2}, \dots, c_{s+k}\}$  and  $T_2 = \{c_{s+k+1}, c_{s+k+2}, \dots, c_{s+2k=q}\}$  form an  $(q - 2k, k)$  partition of  $C$ .
- So,  $sp(G) = q - k = \omega(G) - k$ .

Suppose  $sp(G) = \omega(G) - 2k$ .

- Then  $C$  has a  $(q - 2k, k)$ -partition.
- Without loss of generality, assume that  $S = \{c_1, c_2, \dots, c_s\}$ ,  
 $T_1 = \{c_{s+1}, c_{s+2}, \dots, c_{s+k}\}$  and  $T_2 = \{c_{s+k+1}, c_{s+k+2}, \dots, c_{s+2k=q}\}$   
form a  $(q - 2k, k)$  partition of  $C$ .
- Then, by the design of the circuit  $\mathcal{C}$ , assigning the  $k$  input nodes  $X_{s+1, s+k+1}, X_{s+2, s+k+2}, \dots, X_{s+k, s+2k}$  to 1 and the rest to 0 provides a satisfying assignment of size  $k$ .

# Polynomial Time Algorithmic Results

A polynomial time  $3/2$ -approximation algorithm for *certain* 2-split graphs.

## Definition

Let  $\mathcal{G}$  be any graph class. Then  $\mathcal{S}(\mathcal{G})$  denotes the set of those 2-split graphs for which the kernel is in  $\mathcal{G}$ .

## Theorem

*Let  $\mathcal{G}$  be any graph class for which the maximum independent set problem has a polynomial time algorithm. Then MIN STAR PARTITION has a polynomial time  $3/2$ -approximation algorithm for the graph class  $\mathcal{S}(\mathcal{G})$ .*

# The Idea

Let  $G = (C \cup I, E)$  be a 2-split graph with  $|C| = q$ .

- 1 Suppose an optimal star partition of  $G$  has
  - 1  $s_o$  stars with one vertex from  $C$ ;
  - 2  $t_o$  stars with two vertices from  $C$ .
- 2 Then  $sp(G) = s_o + t_o$  and  $s_o + 2t_o = q$ .
- 3 Also this solutions corresponds to an  $(s_o, t_o)$ -partition of  $C$ .

Now consider any  $(s, t)$ -partition of  $C$ .

We will have  $s \geq s_o$  and  $t \leq t_o$ .

Now consider any  $(s, t)$ -partition of  $C$ .

We will have  $s \geq s_o$  and  $t \leq t_o$ .

Let  $\ell = t_o - t \geq 0$ .

Then  $s = s_o + 2\ell$  and  $t = t_o - \ell$ .

(since  $s + 2t = q = s_o + 2t_o$ .)

We have  $s = s_o + 2\ell$  and  $t = t_o - \ell$ . Also

$$t_o - \ell \geq \frac{t_o}{2} \iff \ell \leq \frac{t_o}{2}$$

Suppose  $s_o = 0$ .

- Suppose  $t = t_o - \ell \geq \frac{t_o}{2}$ , then

$$s + t \leq \frac{3}{2}sp(G).$$

Also

$$t_o - \ell \geq \frac{t_o - 1}{2} \iff \ell \leq \frac{t_o + 1}{2}$$

Suppose  $s_o \geq 1$ .

- Suppose  $t = t_o - \ell \geq \frac{t_o - 1}{2}$ , then

$$s + t \leq \frac{3}{2}sp(G).$$



# The Approximation Algorithm

**Algorithm:** *Approximate-2-Split*

**Input:** A 2-split graph  $G = (C \cup I, E)$ .

**Output:** A star partition of  $G$ .

- 1 If  $s_o = 0$ , find an  $(s, t)$ -partition of  $C$  with  $t \geq t_o/2$ .
- 2 If  $s_o \geq 1$ , find an  $(s, t)$ -partition of  $C$  with  $t \geq (t_o - 1)/2$ .
- 3 Output a star partition of  $G$  corresponding to the  $(s, t)$ -partition of  $C$  found.

## Finding a Suitable $(s, t)$ -Partition

Let  $G_K$  be the kernel of the input 2-split graph.

Let  $r = \alpha(G_K)$ .

By property of  $(s_o, t_o)$ -partition:

$$s_o = 0 \implies q = 2t_o \text{ and } r \geq t_o.$$

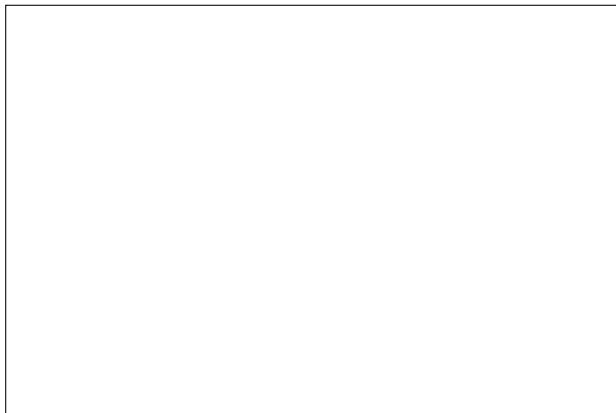
So,

$$s_o = 0 \implies q \text{ is even and } r \geq q/2.$$

And

$$q \text{ is odd or } r < q/2 \implies s_o \geq 1.$$

# Classification of 2-Split Graphs

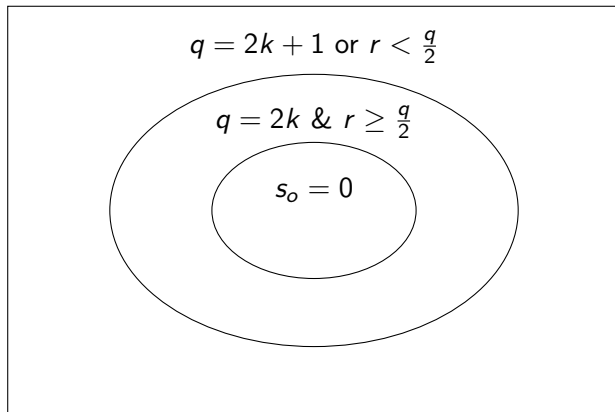


# Classification of 2-Split Graphs

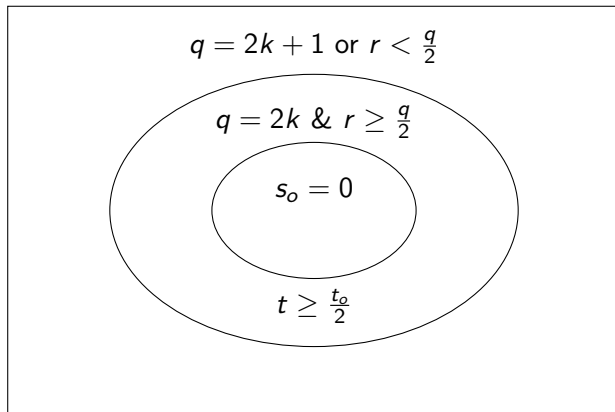
$$q = 2k + 1 \text{ or } r < \frac{q}{2}$$

$$q = 2k \text{ \& } r \geq \frac{q}{2}$$

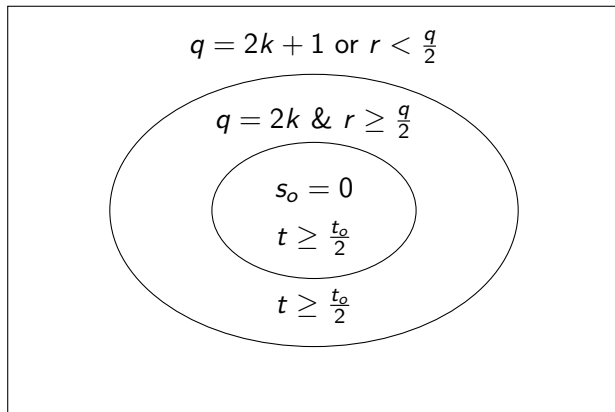
# Classification of 2-Split Graphs



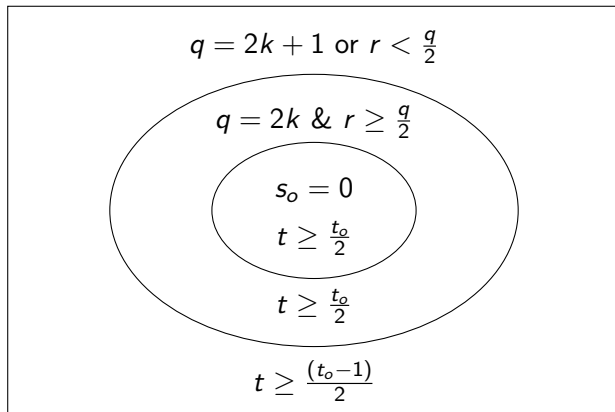
# Classification of 2-Split Graphs



# Classification of 2-Split Graphs



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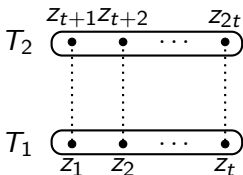




## Idea for Suitable $(s, t)$ -partition

Let  $J = \{z_1, \dots, z_r\}$  be a maximum independent set in the kernel  $G_K$ .

- Let  $t = \lceil r/2 \rceil$ . Then  $t \geq k/2 \geq t_o/2$ .
- Also  $T_1 = \{z_1, \dots, z_t\}$ ,  $T_2 = \{z_{t+1}, \dots, z_{2t}\}$  and  $S = C \setminus (T_1 \cup T_2)$  provides an  $(s, t)$ -partition of  $C$  with  $t \geq t_o/2$ .



# Polynomial Time Algorithms

## Lemma

*Let  $G$  be any graph and let  $I$  be any set of vertices in  $G$  such that any pair of vertices in  $I$  are at distance three or more in  $G$ . Then  $sp(G) \geq |I|$ . Consequently,  $sp(G) \geq \alpha(G^2)$ .*

**Note:** Computing  $\alpha(G^2)$  is NP-hard even for 3-split graphs. This follows from a reduction from the NP-complete EXACT3COVER problem [9].

## Corollary

*Let  $G = (C \cup I, E)$  be a split graph and let  $I_1$  denote the set of all degree one vertices in the independent part  $I$ . Then  $sp(G) \geq |N(I_1)|$ .*

## Corollary

*If  $G = (C \cup I, E)$  is a 1-split graph, then  $|N(I)| = \alpha(G^2)$ .*

## $sp(G)$ for 1-split graph

### Theorem

*If  $G$  is a 1-split graph, then  $sp(G) = \max(\lceil \omega(G)/2 \rceil, \alpha(G^2))$ .*

*Consequently, MIN STAR PARTITION has a linear time exact algorithm for  $(0, 1)$ -split graphs.*

## Further Scope

- Determine the computational complexity of star partition on  $r$ -split graphs for each fixed  $r \geq 3$ .
- It would be interesting to obtain a factor  $3/2$  (or better) polynomial time approximation algorithm for MIN STAR PARTITION on at least *all* of 2-split graphs.
- Designing better than factor 2 approximation algorithms for MIN STAR PARTITION on split graphs remains an interesting algorithmic problem.
- Does STAR PARTITION  $(\omega - k)$  is  $W[3]$ -hard?
- Complexity status remains open even for  $K_{1,4}$ -free split graphs.



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